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SECOND-ORDER BLIND SOURCE SEPARATION: A NEW EXPRESSION OF INSTANTANEOUS SEPARATING MATRIX FOR MIXTURES OF DELAYED SOURCES

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ABSTRACT

In this paper, we study the blind separation of mixtures of propagating waves (delayed sources) encountered for example in underwater telephone (UWT) systems. We suggest a new second-order statistics method using as many observations as sources. First, we show that each of the N delayed sources can be developed as a particular linear combination of the different temporal-derivatives of the N observations.

Under some assumptions, an instantaneous rectangular separating matrix is then identified by the joint diagonalization of a set of covariance matrices estimated from the observations and its derivatives.

The algorithm used takes into account the particular structure of the spectral mixing matrix encountered.

A numerical simulation is provided in a 3-sources/3- observations case for propagating audio signals.

1. INTRODUCTION

Consider a set of N propagating waves $s_j(t)$ in an echo-free and noise-free medium. These are recorded on a set of M identical sensors. Let $x_j(t)$ denote the contribution of the source $s_j(t)$ on a sensor arbitrary indexed by 1, *i.e.* $x_j(t)$ is a filtered version of the source $s_j(t)$. Assuming that the set of sensors is sufficiently compact, then the contribution of the source $s_j(t)$ recorded on a sensor i is the same one as that recorded on the first sensor, except for an attenuation factor and a propagation delay. The observation $y_i(t)$ recorded on the sensor i , is a linear combination of the delayed contribu-

tions $x_j(t)$:

$$\begin{aligned} y_1(t) &= \sum_{j=1}^N x_j(t), \\ y_i(t) &= \sum_{j=1}^N c_{ij} x_j(t - \tau_{ij}), \quad i \in [2, \dots, M], \end{aligned} \quad (1)$$

where c_{ij} is the relative attenuation coefficient of source j on sensor i , and τ_{ij} a relative propagation delay of source j on sensor i .

The different contributions are assumed to be band-limited, differently colored, statistically independent and zero-mean. Thereafter in the paper, the contributions will be called sources.

The problem is to provide an estimation of the N different sources $x_j(t)$ from the observations $y_i(t)$.

A first way to solve the problem using truncated Taylor series of each delayed source $x_j(t - \tau_{ij})$ has been successfully treated in [1]-[5]. It consists of the estimate of an instantaneous square mixing matrix $\mathbf{M}_{M \times M}$ between the observations and the different derivatives of the sources:

$$[y_1, y_2, \dots]^T = \mathbf{M} [x_1, x_2, \dots, \dot{x}_1, \dot{x}_2, \dots]^T.$$

For low delays, second-order statistics are sufficient to extract the different contributions from the observations (see [2], [4], [6]). For higher delays, a combination of two-order and high-order statistics methods is proposed in [3] to achieve the separation.

The main limitation of these methods is the high necessary number of observations (up to several times the number of sources).

We propose here a N -sources N -sensors original approach based on the direct estimation of an instantaneous rectangular

separating matrix \mathbf{S} between the different derivatives of the observations and filtered sources:

$$[x_1^h, x_2^h, \dots, x_N^h]^T = \mathbf{S} [y_1, \dot{y}_1, \dots, y_2, \dot{y}_2, \dots, y_N, \dot{y}_N, \dots]^T,$$

where x_j^h is the source x_j filtered by an invertible known filter h .

It is important to note that the two approaches are not equivalent: the matrix \mathbf{M} is not a simple pseudoinverse of \mathbf{S} .

The paper is organized as follows: in the next section we explain how to construct the separating matrix \mathbf{S} from the propagation model described by the system of equations (1). Then the third section explains the second-order statistics method implemented to estimate this separating matrix. The estimation uses a new version of the joint-diagonalization algorithm proposed by S.Dégerine in [7]. A description of this algorithm has to appear in english, a preprint can already be read in [8]. A numerical simulation in the last section illustrates the effectiveness of our approach.

2. EXPRESSION OF THE SEPARATING MATRIX

In the frequency domain, the system (1) becomes

$$\begin{aligned} Y_1(\nu) &= \sum_{j=1}^N X_j(\nu), \\ Y_i(\nu) &= \sum_{j=1}^N c_{ij} e^{-j2\pi\nu\tau_{ij}} X_j(\nu), \quad i \in [2, \dots, N]. \end{aligned} \quad (2)$$

$X_j(\nu)$ and $Y_i(\nu)$ are respectively the Fourier Transforms (FT) of the j^{th} source and of the i^{th} observation.

The system (2) can be rewritten in matrix notation as:

$$\mathbf{Y}(\nu) = \mathbf{M}^f(\nu) \mathbf{X}(\nu), \quad (3)$$

where

$$\mathbf{Y}(\nu) = [Y_1(\nu), \dots, Y_N(\nu)]^T, \mathbf{X}(\nu) = [X_1(\nu), \dots, X_N(\nu)]^T.$$

The $N \times N$ spectral mixing matrix $\mathbf{M}^f(\nu)$ is defined as:

$$\mathbf{M}^f(\nu) = \begin{bmatrix} 1 & \dots & 1 \\ c_{21} e^{-j2\pi\nu\tau_{21}} & \dots & c_{2N} e^{-j2\pi\nu\tau_{2N}} \\ \vdots & \ddots & \vdots \\ c_{N1} e^{-j2\pi\nu\tau_{N1}} & \dots & c_{NN} e^{-j2\pi\nu\tau_{NN}} \end{bmatrix}. \quad (4)$$

We assume that $\mathbf{M}^f(\nu)$ is regular for any frequency. The inverse matrix of $\mathbf{M}^f(\nu)$ is

$$\mathbf{M}^f(\nu)^{-1} = \frac{1}{\det \mathbf{M}^f(\nu)} (\text{adj } \mathbf{M}^f(\nu))^T,$$

where $\text{adj } \mathbf{M}^f(\nu)$ and $\det \mathbf{M}^f(\nu)$ are respectively the adjoint matrix and the determinant of the matrix $\mathbf{M}^f(\nu)$.

From equation (3), one has:

$$\det \mathbf{M}^f(\nu) \mathbf{X}(\nu) = (\text{adj } \mathbf{M}^f(\nu))^T \mathbf{Y}(\nu). \quad (5)$$

According to the particular structure of the spectral mixing matrix $\mathbf{M}^f(\nu)$, its determinant (denoted by $H_d(\nu)$) is a sum of weighted complex exponentials:

$$H_d(\nu) = \det \mathbf{M}^f(\nu) = \sum_i \beta_i \exp(-j2\pi\nu\tau_{d_i}),$$

where the weights β_i are particular products of coefficients c_{ij} , and τ_{d_i} are particular sums of delays τ_{ij} .

Let $\mathbf{H}(\nu)$ denote the transposed adjoint of $\mathbf{M}(\nu)$. Each entries $H_{kl}(\nu)$ of $\mathbf{H}(\nu)$ can also be expressed as a sum of weighted exponentials:

$$H_{kl}(\nu) = (\text{adj } \mathbf{M}^f(\nu))_{kl}^T = \sum_i \alpha_{kli} \exp(-j2\pi\nu\tau_{kli}),$$

where the weights α_{kli} are also particular products of coefficients c_{ij} , and τ_{kli} are particular sums of delays τ_{ij} .

Back to the temporal representation, the system (5) becomes:

$$\{h_d * x_k\}(t) = \sum_{l=1}^N \{h_{kl} * y_l\}(t),$$

where $h_{kl}(t) = \text{FT}^{-1}(H_{kl}(\nu))$, $h_d(t) = \text{FT}^{-1}(H_d(\nu))$ and where $\{h * x\}(t) = \int h(t - \tau)x(\tau)d\tau$ denotes the convolution of $h(t)$ and $x(t)$.

Each filtered source $\{h_d * x_k\}(t)$ is then a finite sum of delayed observations:

$$\{h_d * x_k\}(t) = \sum_{l,i} \alpha_{kli} y_l(t - \tau_{kli}). \quad (6)$$

Assuming that the τ_{kli} are "small" for all indices, $y_l(t - \tau_{kli})$ can be approximated by its truncated up to P-order Taylor series expansion. Each filtered source can be then approximated by a linear combination of the observations and its derivatives:

$$\{h_d * x_k\}(t) \approx \sum_{l,i} \alpha_{kli} \sum_{p=0}^P \frac{(-\tau_{kli})^p}{p!} y_l^{(p)}(t).$$

For $k = 1, \dots, N$ the system is rewritten as:

$$\mathbf{x}^h(t) \approx \mathbf{S} \tilde{\mathbf{y}}(t), \quad (7)$$

where $\mathbf{x}^h(t) = [x_1^h(t), \dots, x_N^h(t)]^T$ is the filtered sources vector, with $x_k^h(t) = \{h_d * x_k\}(t)$,

$\tilde{\mathbf{y}}(t) = [y_1, \dot{y}_1, \dots, y_1^{(P)}, y_2, \dots, y_2^{(P)}, \dots, y_N^{(P)}]^T$ is the observations and their derivatives vector. \mathbf{S} is the $N \times (NP + N)$ separating matrix.

The analytical expression of each entry of \mathbf{S} with respect to the parameters c_{ij} and τ_{ij} is heavy but does not present theoretical difficulties. This expression is detailed in the Appendix A for the 2-sources/2-sensors case.

The joint estimation of the parameters c_{ij}, τ_{ij} and of the separating matrix \mathbf{S} forms the basis of the iterative algorithm proposed in the following section.

3. PRESENTATION OF THE ALGORITHM

From (7) and because the sources $x_k^h(t)$ are mutually uncorrelated, it follows that \mathbf{S} has to diagonalize the set of covariance matrices obtained at different lags $\mathbf{R}_{\tilde{\mathbf{y}}\tilde{\mathbf{y}}}(\tau_k) = \mathbb{E}\{\tilde{\mathbf{y}}(t)\tilde{\mathbf{y}}^T(t + \tau_k)\}$:

$$\mathbf{S}\mathbf{R}_{\tilde{\mathbf{y}}\tilde{\mathbf{y}}}(\tau_k)\mathbf{S}^T = \mathbf{\Lambda}(\tau_k), \quad \forall \tau_k$$

$\mathbf{\Lambda}(\tau_k) = \mathbb{E}\{\mathbf{x}^h(t)\mathbf{x}^{hT}(t + \tau_k)\}$ being a diagonal matrix whatever the lag τ_k .

S. Dégerine propose in [7],[8] a new algorithm (called Least Square on B or LSB) for approximate non-orthogonal joint diagonalization of a set of matrices. In its original form, this algorithm iteratively searches an optimal joint diagonalizer $\tilde{\mathbf{S}}$ of a set of K matrices to the mean square sense. The second-order criterion to be optimized is then

$$C(\tilde{\mathbf{S}}) = \sum_k \text{Off}(\tilde{\mathbf{S}}\mathbf{R}_{\tilde{\mathbf{y}}\tilde{\mathbf{y}}}(\tau_k)\tilde{\mathbf{S}}^T), \quad (8)$$

where $\text{Off}(\cdot)$ is the sum of the square non diagonal elements of the considered matrix. To perform the mean square optimization, S. Dégerine uses a relaxation on the lines of $\tilde{\mathbf{S}}$ conducting to solve N eigenvalue problems for each iteration.

Here, the expected diagonalizer \mathbf{S} being non square, the optimization (8) does not conduct to a unique solution for $\tilde{\mathbf{S}}$. The main idea is then to force the algorithm to hold the theoretical structure of the separation matrix at each iteration. This theoretical expression depends on the parameters c_{ij} and τ_{ij} . At each step of relaxation, we estimate the parameters c_{ij} and τ_{ij} from their formal expression wrt the entries of the current estimated $\tilde{\mathbf{S}}$. The next step is processed using a new $\tilde{\mathbf{S}}$ built on these estimated parameters.

An illustration of such theoretical expressions can be found in Appendices for the 2-sources case. For the N -sources case, we implemented formal calculus subroutine in order to provide automatically the formal expressions we need.

The final algorithm is summed up as follows:

Numerical Algorithm

- 1) From the observations $\mathbf{y}(t)$, build the observation vector $\tilde{\mathbf{y}}(t)$ at the order P .
- 2) Compute K covariance matrix $\mathbf{R}_{\tilde{\mathbf{y}}\tilde{\mathbf{y}}}(\tau_k)$.
- 3) Initialize $\tilde{\mathbf{S}}(0)$ with arbitrary values.
- 4) Proceed to an iteration k with LSB algorithm.
- 5) From $\tilde{\mathbf{S}}(k)$ obtained at step 4), estimate the attenuation coefficients c_{ij}^k and the propagation delays τ_{ij}^k .
- 6) From c_{ij}^k and τ_{ij}^k , compute a new matrix $\tilde{\mathbf{S}}(k + 1)$.
- 7) Repeat steps 4), 5) and 6) until the evolution of the estimated matrix $\tilde{\mathbf{S}}$ becomes sufficiently weak.

4. RESULTS

We present now a numerical simulation in the 3-sources/3-observations case. The sources are 24s long music extracts. The sampling frequency is $F_s = 22.05kHz$.

The matrix \mathbf{C} of relative attenuations is:

$$\mathbf{C} = \begin{bmatrix} 1.0000 & 1.0000 & 1.0000 \\ 2.0000 & 1.3000 & 1.2000 \\ 3.0000 & 1.6000 & 2.2000 \end{bmatrix}.$$

The matrix \mathbf{D} of relative propagation delays is:

$$\mathbf{D} = \begin{bmatrix} 0 & 0 & 0 \\ 30.00\mu s & 18.00\mu s & 5.00\mu s \\ 25.00\mu s & 12.50\mu s & 10.00\mu s \end{bmatrix}.$$

For the 3 observations, we take a Taylor series expansion up to 3-order ($P = 3$). 151 covariance matrices $\mathbf{R}_{\tilde{\mathbf{y}}\tilde{\mathbf{y}}}(\tau_k)$ are used ($K = 151$), with $\tau_k = k/F_s$, $k \in \{-75, 75\}$.

Fig. 1 (a) shows the evolution of the optimization criterion $C(\tilde{\mathbf{S}})$ at each iteration number i and part (b) presents the Frobenius norm of the matrix $\tilde{\mathbf{S}}(k + 1) - \tilde{\mathbf{S}}(k)$

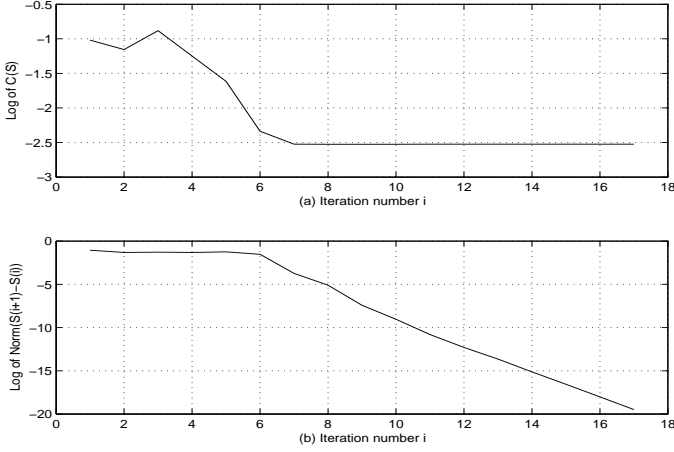


Fig. 1. Convergence

After convergence (8 iteration steps), we obtain the following estimations for the relative attenuations and for the relative propagation delays:

$$\tilde{\mathbf{C}} = \begin{bmatrix} 1.0000 & 1.0000 & 1.0000 \\ 1.9995 & 1.3047 & 1.1967 \\ 2.9998 & 1.6053 & 2.1929 \end{bmatrix},$$

$$\tilde{\mathbf{D}} = \begin{bmatrix} 0 & 0 & 0 \\ 31.64\mu s & 18.87\mu s & 5.03\mu s \\ 26.56\mu s & 13.13\mu s & 9.81\mu s \end{bmatrix}.$$

Taking the matrices $\tilde{\mathbf{C}}$ and $\tilde{\mathbf{D}}$ into account, the filter $H_d(\nu)$ can be identified and its effect reversed after separation. We obtain the following source estimations (Fig. 2) that have to be compared to the original ones (Fig. 3).

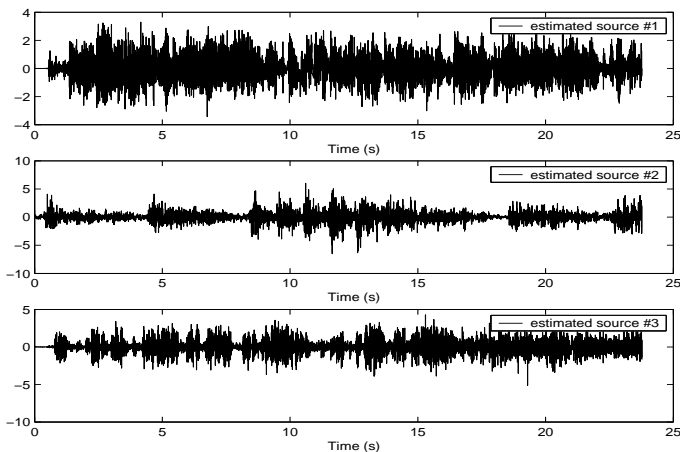


Fig. 2. Estimated sources

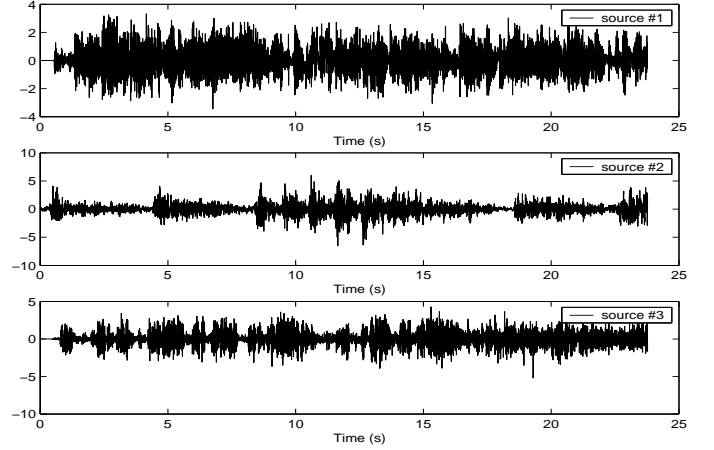


Fig. 3. Original sources

The mean square errors (MSE) between the estimated sources and the original ones and the corresponding Signal to Interference Ratio (SIR) are presented in the Table 1.

	source #1	source #2	source #3
MSE	0.0141	0.0155	0.0164
SIR	41 dB	44 dB	36 dB

Table 1. Performances

5. CONCLUSION

This paper present a novel iterative method for blind source separation from delayed mixtures. The delayed mixtures are approached by instantaneous mixtures of the observation derivatives. This approach uses only second-order statistics and needs no more mixtures than sources. The algorithm is based on the joint diagonalization of a set of spatial covariance matrices but the non square separating matrix is constrained to hold a theoretical structure at each iteration. A numerical simulation shows the efficiency of the approach.

APPENDIX A

FROM $\mathbf{M}^f(\nu)$ TO \mathbf{S} IN THE 2-OBSERVATIONS CASE.

Now, we have the following spectral mixing matrix

$$\mathbf{M}^f(\nu) = \begin{bmatrix} 1 & 1 \\ c_{21}e^{-j2\pi\nu\tau_{21}} & c_{22}e^{-j2\pi\nu\tau_{22}} \end{bmatrix}. \quad (9)$$

In this case (6) leads to the 2 following filtered sources:

$$\begin{aligned} x_1^h(t) &= c_{22}y_1(t - \tau_{22}) - y_2(t), \\ x_2^h(t) &= -c_{21}y_1(t - \tau_{21}) + y_2(t), \end{aligned}$$

where $x_k^h(t) = x_k(t - \tau_{22}) - x_k(t - \tau_{21})$, $k \in [1, 2]$.

With $\mathbf{x}^h(t) = [x_1^h, x_2^h]^T$, and $\tilde{\mathbf{y}}(t) = [y_1, \dot{y}_1, \ddot{y}_1, \dots, y_1^{(P)}, y_2]^T$, the $(2 \times P + 2)$ unmixing matrix of equation (7) becomes:

$$\mathbf{S} = \begin{bmatrix} c_{22} & -c_{22}\tau_{22} & \dots & c_{22}\frac{(-\tau_{22})^P}{P!} & -1 \\ -c_{21} & c_{22}\tau_{21} & \dots & -c_{21}\frac{(-\tau_{21})^P}{P!} & 1 \end{bmatrix}.$$

APPENDIX B

FROM \mathbf{S} TO c_{ij}, τ_{ij} IN THE 2-OBSERVATIONS CASE.

Here, we have the following separating matrix

$$\mathbf{S} = \begin{bmatrix} s_{11} & s_{12} & \dots & s_{1P} & s_{1P+1} \\ s_{21} & s_{22} & \dots & s_{2P} & s_{2P+1} \end{bmatrix},$$

one has the (2×2) spectral separating matrix

$$\mathbf{S}^f(\nu) = \begin{bmatrix} s_{11}^f(\nu) & s_{12}^f(\nu) \\ s_{21}^f(\nu) & s_{22}^f(\nu) \end{bmatrix},$$

where the entries of $\mathbf{S}^f(\nu)$ are polynomials in ν :

$$\begin{aligned} s_{11}^f(\nu) &= \sum_{k=1}^P (2j\pi\nu)^k s_{1k}, \\ s_{12}^f(\nu) &= s_{1P+1}, \\ s_{21}^f(\nu) &= \sum_{k=1}^P (2j\pi\nu)^k s_{2k}, \\ s_{22}^f(\nu) &= s_{2P+1}. \end{aligned}$$

The inverse matrix of $\mathbf{S}^f(\nu)$ is also a matrix of polynomials:

$$[\mathbf{S}^f(\nu)]^{-1} = \frac{1}{\det \mathbf{S}^f(\nu)} \begin{bmatrix} p_{11}(\nu) & p_{12}(\nu) \\ p_{21}(\nu) & p_{22}(\nu) \end{bmatrix}.$$

An approximation of the spectral mixing matrix $\mathbf{M}^f(\nu)$ is obtained normalizing each column of the previous matrix by $p_{1k}(\nu)$

$$\mathbf{M}^f(\nu) \approx \begin{bmatrix} 1 & 1 \\ p_{21}(\nu)/p_{11}(\nu) & p_{22}(\nu)/p_{12}(\nu) \end{bmatrix}.$$

The entries of the second line of this matrix can be developed in power series expansion in ν :

$$\begin{aligned} p_{21}(\nu)/p_{11}(\nu) &= q_0 + q_1\nu + O^2(\nu), \\ p_{22}(\nu)/p_{12}(\nu) &= r_0 + r_1\nu + O^2(\nu). \end{aligned}$$

Identifying these expansions with the Taylor-series expansion of the entries of $\mathbf{M}^f(\nu)$ (see 9) we find:

$$\begin{aligned} c_{21} &= q_0, \\ \tau_{21} &= -\frac{1}{j2\pi} \frac{q_1}{q_0}, \\ c_{22} &= r_0, \\ \tau_{22} &= -\frac{1}{j2\pi} \frac{r_1}{r_0}. \end{aligned}$$

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